

Gaussian Random Variables

$$X \sim \mathcal{N}(\mu, \sigma^2)$$

$$\mathbb{E}[X] = \mu \quad \mathbb{V}[X] = \sigma^2$$

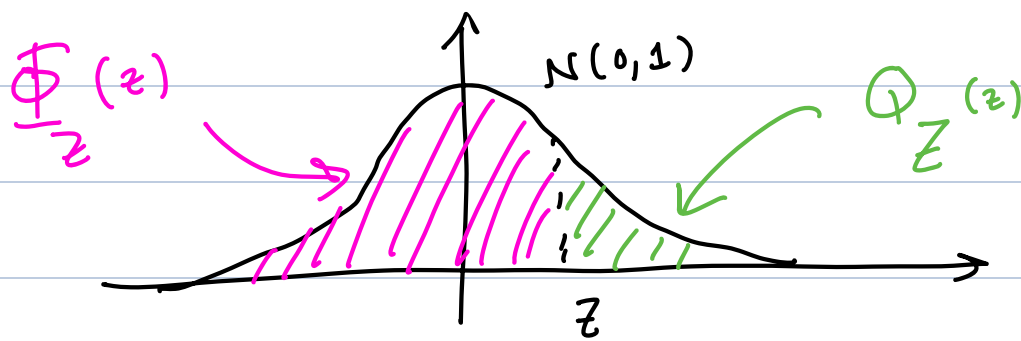
$$Z \sim \mathcal{N}(0, 1)$$

$$X = \mu + \sigma Z$$

→ Cumulative distribution function (CDF)

↳ left-tail probability

$$\begin{aligned} \Phi_Z(z) &= \mathbb{P}(Z \leq z) \\ &= \int_{-\infty}^z \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{t^2}{2}\right) dt \end{aligned}$$



→ Complementary CDF (Survival function)

$$\begin{aligned}
 Q_z(z) &= 1 - \Phi_z(z) = \mathbb{P}(\underline{\underline{Z > z}}) \\
 &= \int_z^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{t^2}{2}\right) dt
 \end{aligned}$$

→ What is the CDF of a non-central Gaussian?

$$X \sim N(\mu, \sigma^2)$$

$$\begin{aligned}
 \mathbb{F}_X(x) &= \mathbb{P}(X \leq x) \\
 &= \mathbb{P}(\mu + \sigma Z \leq x)
 \end{aligned}$$

$$= P\left(z \leq \frac{x-\mu}{\sigma}\right)$$

$$= \Phi_z\left(\frac{x-\mu}{\sigma}\right)$$

Standardization

$$Q_x(x) = Q_z\left(\frac{x-\mu}{\sigma}\right)$$

② Chi-Squared Random Variables

Y is Chi-Squared RV if

$$Y = \sum_{i=1}^2 X_i^2 \sim \chi^2_2$$

where X_i are i.i.d. standard normal random variables

PDF: $p(y) = \frac{1}{2^{v/2} \Gamma(\frac{v}{2})} y^{\frac{v}{2}-1} \exp\left(-\frac{y}{2}\right)$

$y \geq 0$

Chapter 2 (key) Detection Theory

$$Q_{\chi^2_v}(y) = \begin{cases} 2 Q_2(\sqrt{y}), & v=1 \\ e^{-\frac{1}{2}y} \sum_{k=0}^{\frac{v}{2}-1} \frac{(y/2)^k}{k!}, & v \text{ even} \\ \text{~~~~~}, & v \geq 3 \text{ and } v \text{ odd} \end{cases}$$

Hypothesis testing

Idea - Given observed data, we want to decide if a signal is present or not!

We phrase this using a binary hypothesis test:

(null hypothesis)

$$\mathcal{H}_0 : \theta \in \Theta_0$$

$$\begin{aligned} &\mu = 0 \\ &\mu > 0 \\ &\sigma^2 = 1 \end{aligned}$$

(alternative hypothesis)

$$\mathcal{H}_1 : \theta \notin \Theta_0$$

$$\begin{aligned} &\mu \neq 0 \\ &\mu \leq 0 \\ &\sigma^2 \neq 1 \end{aligned}$$

Ex: Detection of Aircraft in radar

$$\underline{x} = [x_0, x_1, \dots, x_T]^T$$

$$\mathcal{H}_0 : \text{No aircraft} \iff \mu = 0$$

$$\mathcal{H}_1 : \text{There is an aircraft} \iff \mu \neq 0$$

$$\rightarrow \bar{X} = \frac{1}{T} \sum_{t=1}^T X_t \text{ is an informative}$$

statistic for this problem

\rightarrow We can naively decide if an aircraft is present by checking if

$$\bar{X} \geq \gamma$$

Thresholding
the statistic

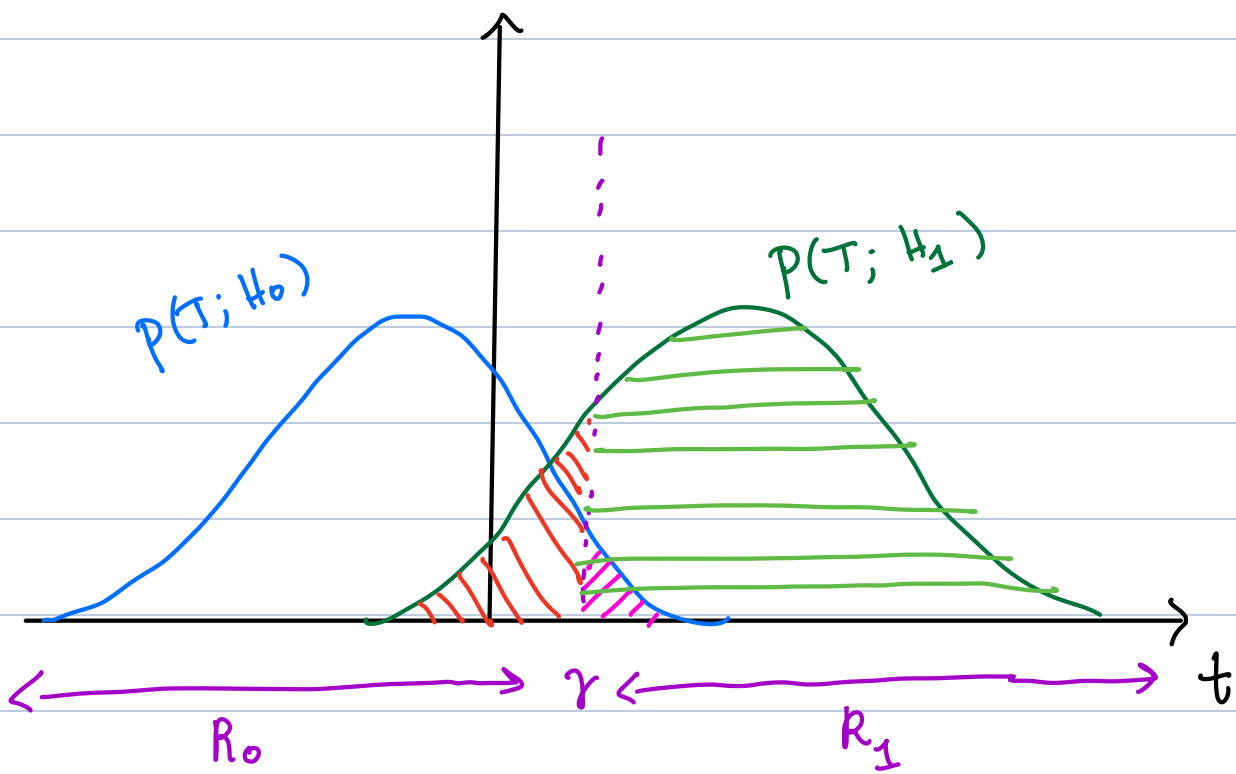
↪ if γ is large, we may never reject the null (type-II error or missed detection)

↪ if γ is too small, we may think the aircraft is almost always present (type-I error or false alarm)

→ Suppose in general we decide \mathcal{H}_1 if $T(\underline{x})$ where $T(\cdot)$ is a statistic surpasses some threshold γ :

→ Let $p(T(\underline{x}); \mathcal{H}_0)$ be the distribution of our statistic under the null hypothesis

→ Let $p(T(\underline{x}); \mathcal{H}_1)$ be the distribution of our statistic under the alternative hypothesis:



False
alarm
probability

$$P_{FA} = P(T(x) > \gamma; H_0) = \int_{\gamma}^{\infty} p(T(x); H_0) dt$$

Missed
detection
probability

$$P_{MD} = P(T(x) < \gamma; H_1) = \int_{-\infty}^{\gamma} p(T(x); H_1) dt$$

Probability
of detection

$$P_D = P(T(x) > \gamma; H_1) = \int_{\gamma}^{\infty} p(T(x); H_1) dt$$

Hypothesis test is just an optimization problem

↳ want to find a statistic and threshold such that I maximize P_D subject to

$$P_{FA} = \alpha$$

A detector is function defined as follows:

$$\delta(\underline{x}) = \begin{cases} \text{"Reject null"}, & T(\underline{x}) > \gamma \\ \text{"Retain null"}, & T(\underline{x}) \leq \gamma \end{cases}$$

$T(\underline{x}) \in R_1$
 $T(\underline{x}) \in R_0$

Neyman - Pearson

To maximize P_D for a given

$P_{FA} = \alpha$, decide H_1 if

$$L(\underline{x}) \triangleq \frac{p(\underline{x}; H_1)}{p(\underline{x}; H_0)} > \gamma$$

↳ likelihood ratio

where the threshold γ is found from:

$$P_{FA} = \int_{\{\underline{x}: L(\underline{x}) > \gamma\}} p(\underline{x}; H_0) d\underline{x} = \alpha$$

→ This lemma is anagously referred to as the likelihood ratio test

→ COOL THING: If a sufficient statistic for a random sample exists, the likelihood ratio will be a function of the sufficient statistic

Example: $X_i \stackrel{iid}{\sim} N(\mu, \sigma^2)$
↑ unknown
↑ known

$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$ is a sufficient
statistic

Proof: We define the Lagrangian:

$$L = P_D + \lambda (P_{FA} - \alpha), \quad \lambda < 0$$

$$= \int_{R_1} P(x; H_1) dx + \lambda \left(\int_{R_1} P(x; H_0) dx - \alpha \right)$$

$$= \int_{R_1} p(x; H_1) + \lambda p(x; H_0) dx - \lambda \alpha$$

when is
the integrand
is positive

$$p(x; H_1) + \lambda p(x; H_0) > 0$$

$$R_1 = \left\{ \frac{p(x; H_1)}{p(x; H_0)} > \boxed{-\lambda} \right\}$$

The Lagrange multiplier can tell us what the threshold should be \rightarrow can be found directly by solving the constraint

$$P_{FA} = \int_{R_1} p(x; H_0) dx = \alpha$$

Example 3.2 - DC Level in White Gaussian Noise (WGN)

We want to consider the following detection problem:

$$H_0: x_i \sim N(0, \sigma^2), \quad i=1, \dots, n$$

$$H_1: x_i \sim N(\mu, \sigma^2), \quad i=1, \dots, n$$

Assume μ and σ^2 are known quantities.

To characterize the detector, we should compute the likelihood ratio:

$$L(x_{1:n}) = \frac{p(x_{1:n}; H_1)}{p(x_{1:n}; H_0)} = \frac{\prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x_i - \mu)^2}{2\sigma^2}\right)}{\prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{x_i^2}{2\sigma^2}\right)}$$

$$= \frac{\exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2\right)}{\exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n x_i^2\right)} > \gamma$$

$$= \exp\left(-\frac{1}{2\sigma^2}\left(\sum_{i=1}^n (x_i - \mu)^2 - \sum_{i=1}^n x_i^2\right)\right) > \gamma$$

Take the logarithm of both sides

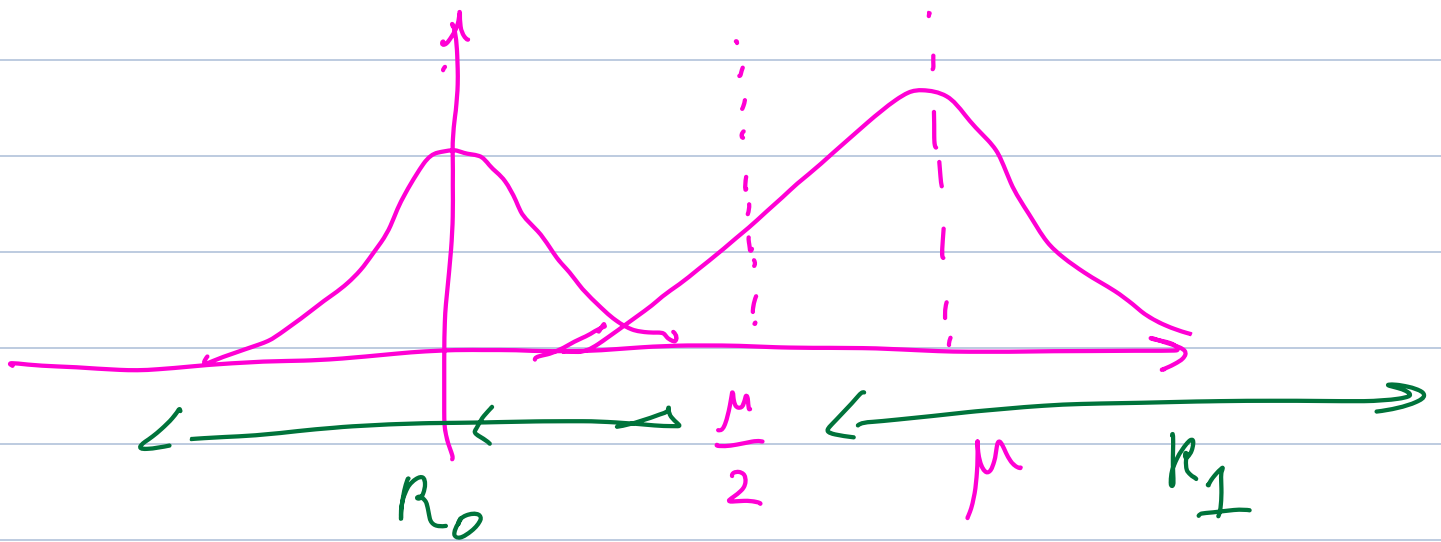
$$-\frac{1}{2\sigma^2}\left(\sum_{i=1}^n \cancel{x_i^2} - 2x_i\mu + \mu^2 - \sum_{i=1}^n \cancel{x_i^2}\right) > \log \gamma$$

$$= -\frac{1}{2\sigma^2}\left(-2\mu \sum_{i=1}^n x_i + n\mu^2\right) > \log \gamma$$

$$= \frac{\mu}{\sigma^2} \sum_{i=1}^n x_i - \frac{n\mu^2}{2\sigma^2} > \log \gamma$$

$$= \frac{\mu}{\sigma^2} \sum_{i=1}^n x_i > \log \gamma + \frac{n\mu^2}{2\sigma^2}$$

$$\Leftrightarrow \frac{1}{n} \sum_{i=1}^n x_i > \underbrace{\frac{\sigma^2}{n\mu} \log \gamma + \frac{\mu}{2}}_{\gamma'}$$



Suppose, I want to set $P_{FA} = \alpha$

our detector:

$$\bar{X} \geq \gamma'$$

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n x_i \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$

likelihood of our test statistic under the null

$$P_{FA} = \int_{\gamma'}^{\infty} p(T(\underline{x}); H_0) dt$$

region R_1 (where we reject null)

$$T(\underline{x}) = \bar{X} = \frac{1}{n} \sum_{i=1}^n x_i \quad x_i \stackrel{iid}{\sim} N(0, \sigma^2)$$

$$\bar{X}; H_0 \sim N\left(0, \frac{\sigma^2}{n}\right)$$

$$P_{FA} = \alpha = Q_Z \left(\frac{\gamma'}{\sigma/\sqrt{n}} \right)$$

$$Q_Z^{-1}(\alpha) = \frac{\gamma'}{\sigma/\sqrt{n}} \Rightarrow \boxed{\gamma' = \frac{\sigma Q_Z^{-1}(\alpha)}{\sqrt{n}}}$$

Example 2 (3.3 in Detection Book)

$$H_0: X_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_0^2) \quad i=1, \dots, n$$

$$H_1: X_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_1^2) \quad i=1, \dots, n$$

$\sigma_1^2 > \sigma_0^2$ both known

$$L(\underline{x}) = \frac{p(x_{1:n}; H_1)}{p(x_{1:n}; H_0)} = \frac{\prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma_1^2}} \exp\left(-\frac{x_i^2}{2\sigma_1^2}\right)}{\prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma_0^2}} \exp\left(-\frac{x_i^2}{2\sigma_0^2}\right)}$$

$$= \frac{(2\pi\sigma_1^2)^{-n/2}}{(2\pi\sigma_0^2)^{-n/2}} \cdot \frac{\exp\left(-\frac{1}{2\sigma_1^2} \sum_{i=1}^n x_i^2\right)}{\exp\left(-\frac{1}{2\sigma_0^2} \sum_{i=1}^n x_i^2\right)}$$

$$\begin{aligned} \log(\cdot) \Rightarrow & -\frac{n}{2} \log(\sigma_1^2) + \frac{n}{2} \log(\sigma_0^2) - \frac{1}{2\sigma_1^2} \sum_{i=1}^n x_i^2 \\ & + \frac{1}{2\sigma_0^2} \sum_{i=1}^n x_i^2 > 2\gamma \end{aligned}$$

$$\Rightarrow \left(\sum_{i=1}^n x_i^2 \right) \left(\frac{1}{\sigma_0^2} - \frac{1}{\sigma_1^2} \right) > 2\gamma + n \log(\sigma_1^2) - n \log(\sigma_0^2)$$

$$Y = \sum_{i=1}^n x_i^2 > \frac{2\gamma + n \log(\sigma_1^2) - n \log(\sigma_0^2)}{\left(\frac{1}{\sigma_0^2} - \frac{1}{\sigma_1^2} \right)}$$

just for intuition

$$\frac{1}{n} \sum_{i=1}^n x_i^2 > \frac{2\gamma + n \log(\sigma_1^2) - n \log(\sigma_0^2)}{n \left(\frac{1}{\sigma_0^2} - \frac{1}{\sigma_1^2} \right)}$$

$X_i \sim N(0, \sigma_0^2)$ under null

$X_i \sim N(0, \sigma_1^2)$ under alternative

$$P_{FA} = \alpha = \int_{\gamma'}^{\infty} p(y; H_0) dy$$

$$Y' = \frac{1}{\sigma_0^2} \sum_{i=1}^n x_i^2 = \sum_{i=1}^n \left(\frac{x_i}{\sigma_0} \right)^2$$

$$X_i \sim N(0, \sigma_0^2)$$

$$\frac{x_i}{\sigma_0} \sim N(0, 1)$$

Then $Y' \sim \chi_n^2 \Rightarrow Q_{\chi_n^2} \left(\frac{\gamma'}{\sigma_0^2} \right) = \alpha$

↑
degrees
of freedom

$$\gamma' = \sigma_0^2 Q_{\chi_n^2}^{-1}(\alpha)$$

Bayesian Approach

$$\begin{aligned} P(\text{ERROR}) &= \underbrace{P(\text{reject null} \mid \text{null is true})}_{H_1} \underbrace{P(\text{null is true})}_{H_0} \\ &\quad + \underbrace{P(\text{retain null} \mid \text{null is not true})}_{H_0} \underbrace{P(\text{null is not true})}_{H_1} \\ &= P(H_1 \mid H_0) P(H_0) + P(H_0 \mid H_1) P(H_1) \end{aligned}$$

Maximum likelihood detector : $P(H_0) = P(H_1) = \frac{1}{2}$

$$\frac{p(\underline{x} \mid H_1)}{p(\underline{x} \mid H_0)} > 1$$

Maximum a posteriori (MAP) detector $P(H_0) \neq P(H_1)$

$$\frac{p(x | H_1)}{p(x | H_0)} > \frac{p(H_0)}{p(H_1)}$$

Bayes Risk : The Bayes risk R is defined as :

$$R = \mathbb{E}[\text{Cost}] = \sum_{i=0}^1 \sum_{j=0}^1 C_{ij} P(H_i | H_j) P(H_j)$$

Cost matrix $C = \begin{bmatrix} C_{00} & C_{01} \\ C_{10} & C_{11} \end{bmatrix}$

The detector that minimizes the Bayes risk is to decide H_1 if:

Bayes detector

$$\frac{p(x | H_1)}{p(x | H_0)} > \frac{(C_{10} - C_{00}) P(H_0)}{(C_{01} - C_{11}) P(H_1)}$$

The reason the Bayes risk perspective is nice is because it is easily extendable to multiple hypothesis testing:

$$R = \sum_{i=0}^{M-1} \sum_{j=0}^{M-1} C_{ij} P(H_i | H_j) P(H_j)$$

Special case : $C_{ii} = 0$
 $C_{ij} = 1$ for all $i \neq j$

Then

$$R = \sum_{i=0}^{M-1} \sum_{j=0}^{M-1} P(H_i | H_j) P(H_j)$$

What is the decision rule?

For each possible decision \rightarrow choose H_k

$$k=0, \dots, M-1 \quad \left[C_k(x) = \sum_{j=0}^{M-1} C_{kj} P(x | H_j) P(H_j) \right]$$

Decision rule is to choose the H_k such that C_k is minimized